9: Advanced shading techniques

Obtaining realistic renderings in real-time!

Remember the Phong's local model... [Phong CACM 1975]





$$L(\mathbf{p} \to \mathbf{e}) = K_a + \sum_{s} [K_d(\mathbf{n} \cdot \boldsymbol{\ell}) + K_s(\mathbf{r} \cdot \mathbf{e})^n] I_s$$

ambiant diffuse specular

... varying materials via the use of textures



Use textures for more than material effects

- to modify surface appearance
- to modify lighting properties

$$L(\mathbf{p} \rightarrow \mathbf{e}) = K_a + \sum_s [K_d(\mathbf{n} \ \boldsymbol{\ell}) + K_s(\mathbf{r} \cdot \mathbf{e})^n]_s$$

- Normal mapping
- Bump mapping
- Parallax mapping
- Displacement mapping

*** Normal mapping ***

Goal: locally perturb normals to create the illusion of modified geometry





*** Normal mapping ***

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*** Normal mapping ***

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In practice:

- normals stored in the "tangent space"
- requires transformation matrix
 - from world to tangent space
 - (or inversely)
- Tangents computed as a pre-process
 - according to tex coords derivatives
 - see <u>http://www.terathon.com/code/tangent.html</u>
 - stored as a new per-vertex attribute





*** Normal mapping ***

Goal: locally perturb normals to create the illusion of modified geometry

In practice (GPU side):

- Given original normal N and tangent T
- Compute the binormal vector:

$$B = N \times T$$

• Build the TBN matrix:

 $\begin{pmatrix} T_x & B_x & N_x \ T_y & B_y & N_y \ T_z & B_z & N_z \end{pmatrix}$

- Transform a vector **v**
 - from tangent to world: $v_w = TBN v_t$
 - from world to tangent: $v_t = TBN v_w$





*** Bump mapping ***

Same principle: but uses a depth (grey-level) map as input



In practice:

- Compute normals from the depth (using finite differences)
- Apply the normal mapping method

*** Parallax mapping ***

Same goal, but more realistic

• Bump/normal mapping does not fetch the good depth/normal values



In practice:

- walk along the (projected) view vector
- detect the right values at the intersection between the view and perturbed heightfield
- apply the normal mapping approach
- more info: <u>http://sunandblackcat.com/tipFullView.php?l=eng&topicid=28</u>

*** Parallax mapping ***

Same goal, but more realistic



without

*** Parallax mapping ***

Same goal, but more realistic



*** Displacement mapping ***

Goal: actually displace vertices!

normal mapping







*** Displacement mapping ***

Goal: actually displace vertices!

displacement mapping





*** Displacement mapping ***

Goal: actually displace vertices!

In practice:

- move vertices along their normals
- requires highly tessellated meshes
 - rely on adaptive tesselation
 - using the tesselation shader



- Environment mapping
- Prefiltered environment maps
- Ambient occlusion
- Shadow mapping

*** Environment mapping

Goal: realistic reflections/refractions

latitude-longitude map



cube map

light probe

*** Environment mapping

Goal: realistic reflections/refractions

In practice:

- Create the texture
 - acquired (using HDR photos of a mirrored sphere for instance)
 - \circ or synthesized in real-time
- Using the reflected/refracted vector
 - compute the corresponding coordinates (spherical/cube/probe)
 - fetch texture color (basically 2 lines of code)





*** Environment mapping

Goal: realistic reflections/refractions



Reflection

Refraction

*** Prefiltered environment mapping ***

Goal: realistic glossy reflections/refractions, diffuse surfaces



*** Prefiltered environment mapping ***

Goal: realistic glossy reflections/refractions, diffuse surfaces





*** Prefiltered environment mapping ***

Goal: realistic glossy reflections/refractions, diffuse surfaces

For pure diffuse surfaces:

• Low-frequency image



- can be represented with a few coefficients of refinable basis functions
 - e.g. spherical harmonics



*** Prefiltered environment mapping ***

Goal: realistic glossy reflections/refractions, diffuse surfaces

For pure diffuse surfaces:



- 9 coefficients sufficient
- can be pre-computed **for each vertex** (as attributes)! and evaluated in real-time

*** ambient occlusion ***

Goal: compute (averaged) visibility at each surface point [Miller 94]

Modify lighting effects *** ambient occlusion ***

Goal: compute (averaged) visibility at each surface point [Miller 94]

autodesk.com

Original model

With ambient occlusion

Extracted ambient occlusion map

*** ambient occlusion ***

Goal: compute (averaged) visibility at each surface point [Miller 94]

More and more screen-space solutions/approximations:

- allows dynamic scenes/anim/deformations
- based on depth + normal maps

https://www.youtube.com/watch?time_continue=27&v=-IFxjKT7MXA https://en.wikipedia.org/wiki/Screen_space_ambient_occlusion http://john-chapman-graphics.blogspot.fr/2013/01/ssao-tutorial.html

*** Shadow mapping ***

Modify lighting effects *** Shadow mapping ***

Goal: create cast shadows

http://www.opengl-tutorial.org/intermediate-tutorials/tutorial-16-shadow-mapping/

*** Shadow mapping ***

- draw scene from light
 - \circ store depth in a texture
 - $\circ \rightarrow$ called shadow map

*** Shadow mapping ***

- 1: draw scene from light
 - \circ store depth in a texture
 - $\circ \rightarrow$ called shadow map

- 2: draw scene from camera
 - compute lighting (as usual)
 - project each point in the **light space**
 - compare depth with the one fetched in the shadow map
 - if farther: in the shadow!

*** Shadow mapping ***

- Some issues:
 - \circ acne effect \rightarrow require small bias

*** Shadow mapping ***

Goal: create cast shadows

- Some issues:
 - \circ acne effect \rightarrow require small bias
 - \circ shadow map resolution \rightarrow cascaded shadow maps

http://ogldev.atspace.co.uk/www/tutorial49/tutorial49.html

Playing with images

Plenoptic function [Adelson and Bergen 91]

 $P(\theta, \phi, \lambda, t, V_x, V_y, V_z)$

- P defines the intensity as a function of viewpoint, time, wavelength
- capture all possible images around p
- \rightarrow Image Based Rendering (IBR) = reconstruct P from samples

Playing with images *** light fields ***

Example: light field acquisition

Stanford Multi-Camera Array 125 cameras using custom hardware [Wilburn et al. 2002, Wilburn et al. 2005]

Distributed Light Field Camera 64 cameras with distributed rendering [Yang et al. 2002]

Playing with images

*** relighting ***

Example: relighting

Playing with images *** relighting ***

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Playing with images

*** relighting ***

Example: relighting

more: https://www.youtube.com/watch?v=piJ4Zke7EUw