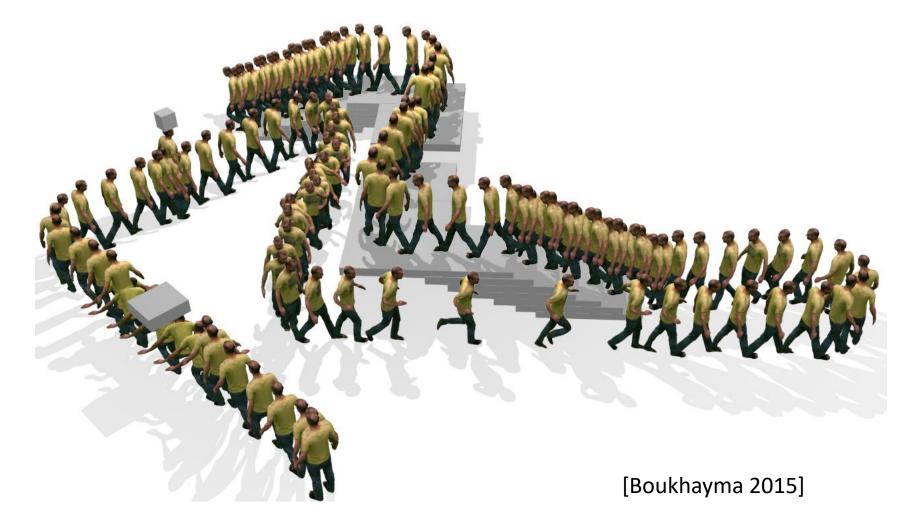
Advanced Animation



Topics

- 1. Advanced & non-rigid capture techniques
- 2. Data driven content reanimation
- 3. Layered animation models for complex scenes

Advanced & non-rigid capture techniques

Remember: Motion capture

- Capture animation based on actor movements
- Traditionally based on markers
- Traditionally used to infer kinematic bone movement

Limitations

- Density: going beyond bones
- Combining different motions
- Adapt to different morphologies



Difficulties with traditional pipelines

- Manually define animation trajectories
- Traditional capture helps but still requires manual intervention
- Animating non rigid objects is still tedious (faces, clothes...)
- Requires expertise and time, expensive



Source: Felix Ferrand

Automatic dense capture

Main ideas

- Recover 3D motions with little or no manual input
- Densely observe real shapes for non-rigid effects
- Solve an alignment problem, between
 - 1. A digital 3D deformable model
 - 2. Real shape surface trajectories observed

Challenges

- How to define a proper deformable model?
- How to match trajectories between real and digital model?
 - Huge search space : model vertices vs sensor data
- How to properly constrain the motion?
 - Real shapes don't move randomly, can we use this?

Shape alignment principles

- Design or acquire a 3D shape model
 - See previous courses
- Use a low dimensional motion parameterization
 - Element subdivision whose positions parameterizes the motion, or shape subspace model
- Create/identify matching handles
 - Other subdivision, not necessarily same as above
 - Can be landmarks, vertices...

Solving the shape alignment

Algorithm template

- 0. Initialize deformation elements close to observed
- 1. Match model handles to their real counterparts
- 2. Update parameters of deformation to minimize handle distances
- 3. Iterate 1 & 2 until convergence, for each new frame

Note: can be seen as alternating minimization problem argmin E with E = Em + Ed

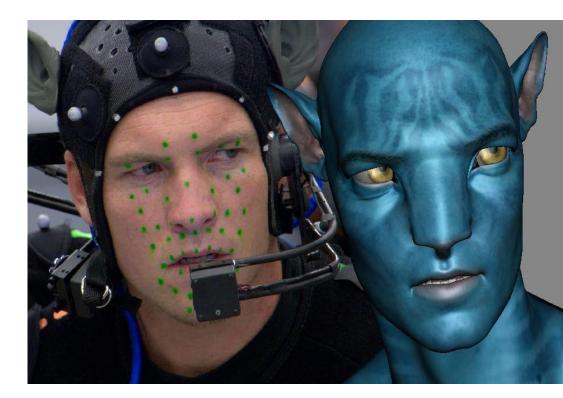
Matching energy. Deformation energy.

Example: face capture

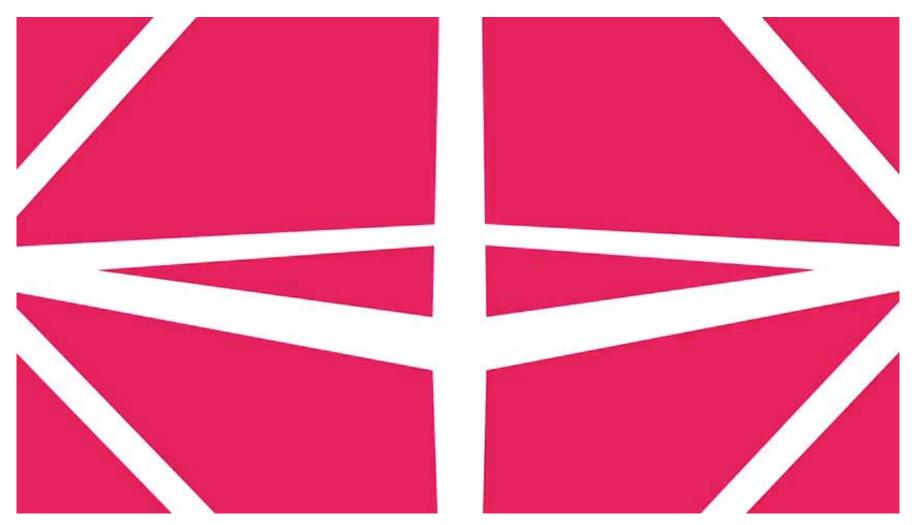
- Observations: manually placed face markers
- Shape model: head and face mesh model
- Deformation model: vertex keys, as rigid as possible energy ...
- Handles: pre-identified face landmarks

Limitations

- Marker occlusion, camera placement
- Manual post-processing usually needed



Face capture illustration

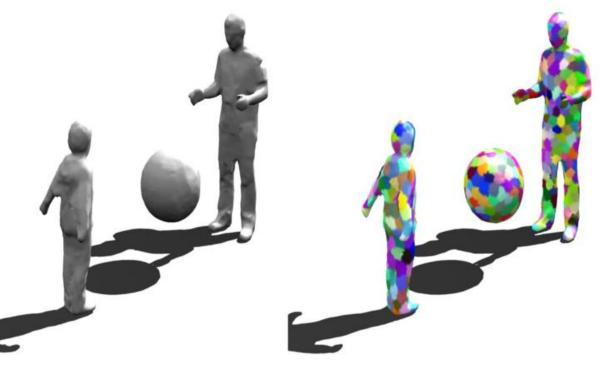


Example: patch-based body deformation capture

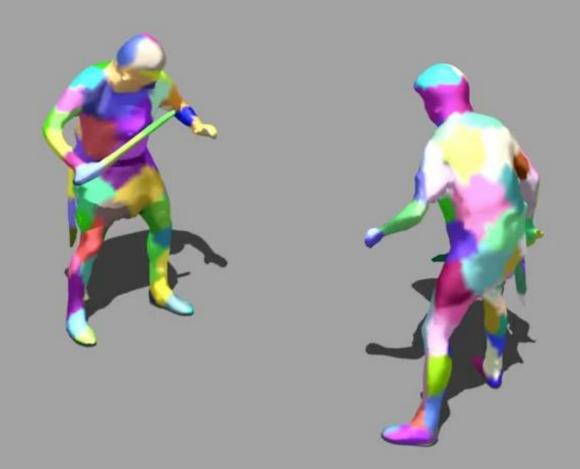
- Observations: silhouettes from multiple cameras
- Shape model: body mesh model
- Deformation model: surface patches with elastic tension
- Handles: surface vertex + silhouette proximity

Limitations

- Geometric fitting only
- Exercise: other limitations?



Patch-based capture example

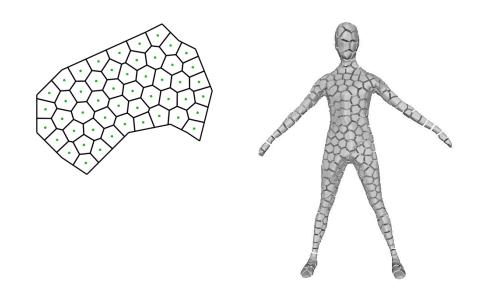


Examples: volume-based deformable shape capture

- Observations: silhouettes from multiple cameras
- Shape model: **volumetric** body mesh model based on CVTs
- Deformation model: volumetric patches with elastic tension
- Handles: surface vertex + silhouette proximity

Limitations

- Geometric fitting only
- Exercise: other limitations?



Volume-based deformable capture example



Data driven content reanimation

Problems

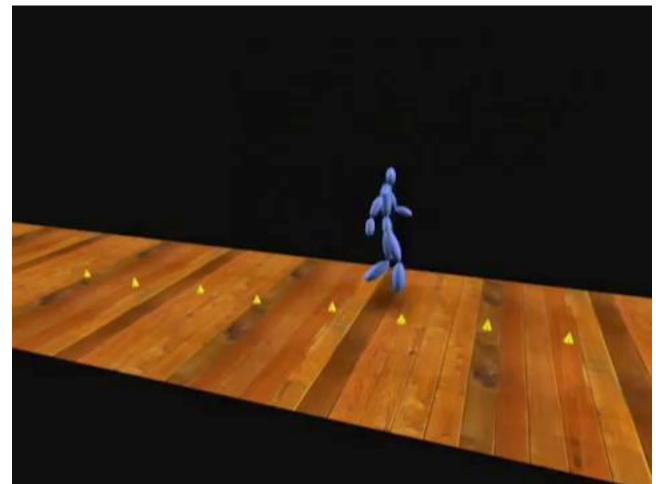
Capture and character animation don't scale well

- Adapt capture to different morphology of virtual character
- Abstract control of animation with many degrees of freedom
- Generate large corpus of data

Can we automate these instead of all manual adaptations?

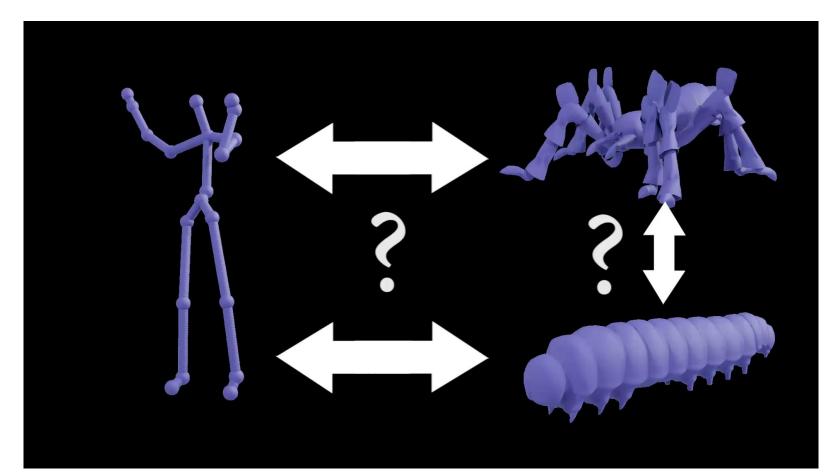
Different morphologies: retargeting

• Principle : preserve angular information of capture and bone lengths of target model [Gleicher 1998]



Animation control: Motion mapping

• Principle : track and detect user movement, remap it to character degrees of freedom [Rhodin 2014]



Generate large corpus: motion graphs

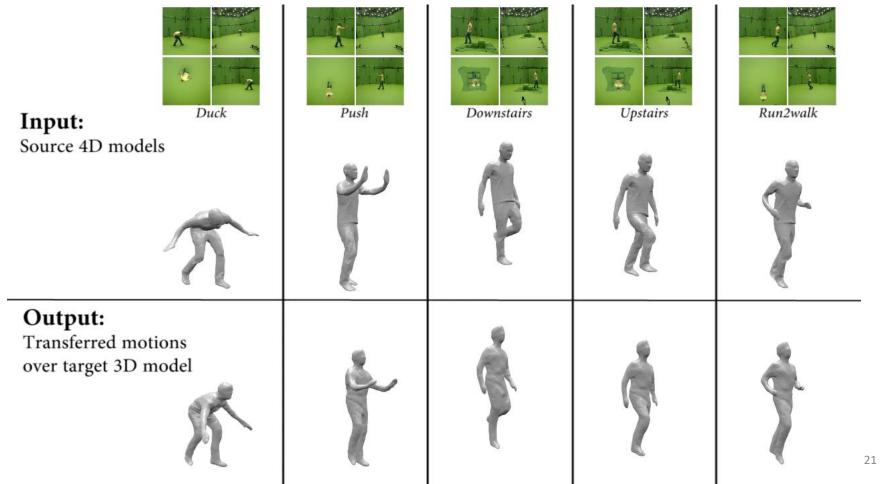
• Principle : build smooth composite sequence from several input sequences of a real captrued character [Boukhayma15]

for the second An and the second s house the second s Essential graph **Output:** constrained composite motion stream Green: original frames

Red : interpolated frames

Generate large corpus: Capture transfer

 Principle : transfer corpus of captures to a different capture with some matching sequences, based on direct sequence regression [Boukhayma16]



Animating Complex Scenes

Animating Complex Scenes

- Grass blowing in the wind, interacting with the feet
- Trees, clouds...
- Characters

Procedural model? Descriptive animation? Geometry / physics?



Animating Complex Scenes

Solution : « layered model»

Successive animation layers each one models a specific feature

- Eases conception & control
- Best model for each layer
- Possible retro-action



Layered models

General methodology

- 1. Observe & identify the sub-phenomena to reproduce
- 2. Represent them independently
 - Choose the best model for each feature Physics, kinematics, geometry, textures...
 - Use different time & space sampling if necessary
- 3. Couple them together

Animation loop

Successive update of each layer + possible retroaction

layered models: case studies 1. Natural phenomena

Examples

- Grass blowing in the wind
- Ocean Waves





View of a walker in real-time?

Difficulties

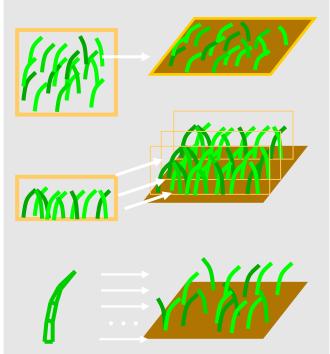
- Number of blades of grass • Rendering: aliasing problems
- Control of the wind

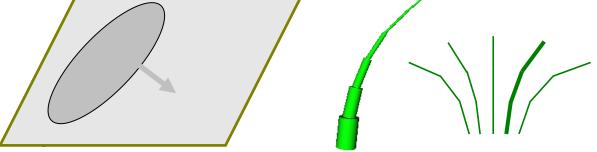
 Breeze, gusp of wind, wirld wind
- Plausible action



Sub-models

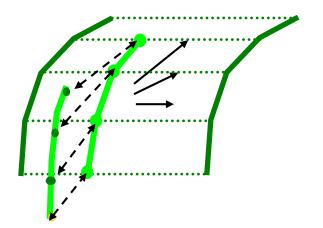
- Grass: 3 levels of detail
- Wind model : mask + action • Breeze, gusp of wind, wirld wind
- Receever : blade of grass o deformations : pre-simulation

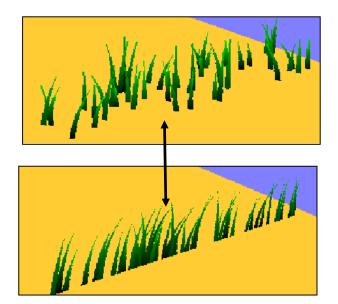




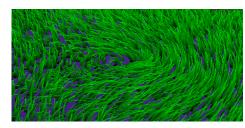
Transitions between levels of details

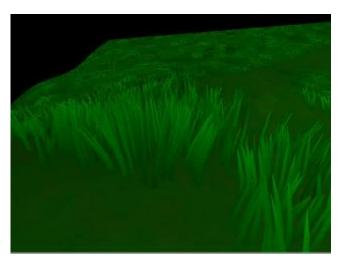
- 3D blades of grass / texture 2D1/2
- texture 2D1/2 / texture





[Perbet Faure Cani 02]







• Aims

Tunable compromise realism/efficiency
 Camera motion
 Unbounded ocean

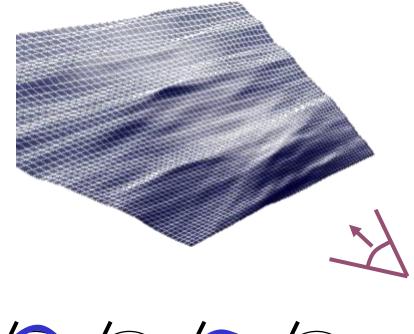
• Difficulties

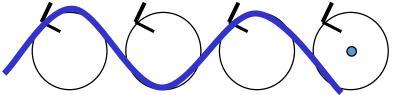
- $\circ \, \text{Complex deformations}$
- \odot Close to far view
- $\circ \text{Aliasing}$



Sub-models

- Receivers
 - \odot Sampled surface
 - \odot Projection of screen pixels
- Wave trains
 - \circ mask + action





Animation : Levels of detail

• Filtering wave trains with the distance Increases efficiency and reduces aliasing





[Hinsinger Neyret Cani, SCA'02]







Case study 2: animated characters

Need of different layers for

- 1. Brain, decision taking
- 2. Moving the skeleton
- 3. Deforming flesh & skin
- 4. Hair
- 5. Clothing

Exo: Which models would you use? Is retro-action necessary?

(walking, gestu

Layer 1: Behavioral model (brain, decision taking)

Example: crowd animation

Particle systems

- Attraction towards an objective
- Repulsive obstacles
- Avoid inter-collisions (fluids)

Techniques from artificial intelligence (AI)

- Individual behavior : rules, emotions, personality
- Social behavior for crowds



Layer 2 : animating the skeleton

From the behavioral model

- 1. Coordinate the different actions (finite automata)
- 2. Call elementary motions

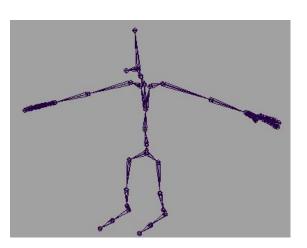
Choose a model for elementary motions

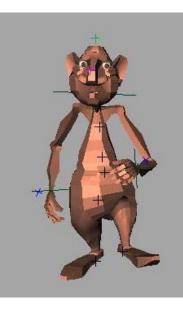
- Descriptive methods
 - Direct and inverse kinematics
 - Motion capture
- Procedural models
 - Physically-based animation + control

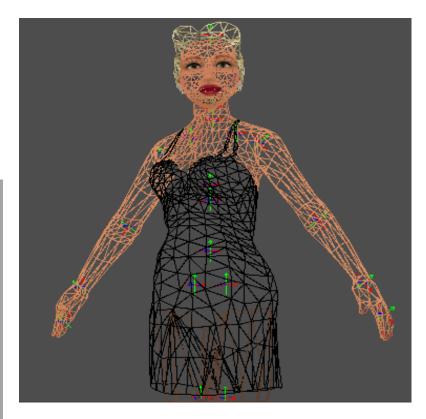


3. Flesh & skin deformation Smooth skinning

- Single mesh
- Deformed by the skeleton (hierarchy of joints)







3. Flesh & skin deformation Key frames vs Blend Shapes

Example of an animated face

• Key frames = Temporal interpolation

 \circ Model and store all successive key- faces

• Blend shapes = Multi-target interpolation

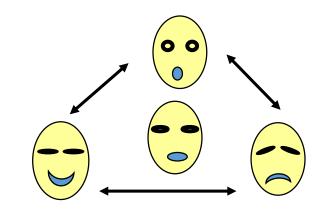
 \odot Model a few « extreme faces » from a « neutral face »

 \odot Animate a trajectory in this space

For each mesh point,

compute successive barycenters on the fly

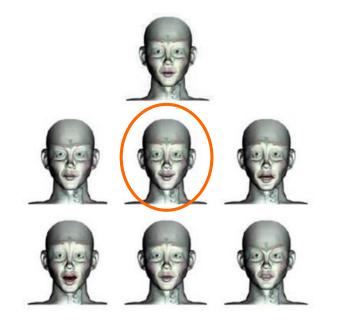


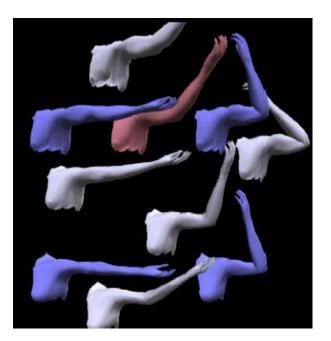


3. Flesh & skin deformation Multi-target interpolation

Advantages

- \odot Fast interpolation
- $\odot\,\text{No}$ need to model something repetitive

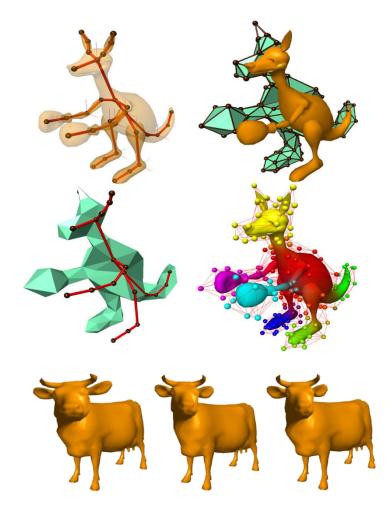




3. Flesh & skin deformation Adding dynamics to the flesh

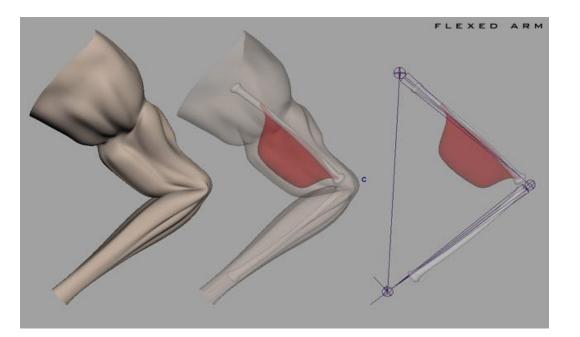
Using finite elements [Capell et al. SIGGRAPH 03]

- Associate each cell with a bone
- Linear elasticity for local models
- Constraints to paste cells together



3. Flesh & skin deformation Anatomical simulation

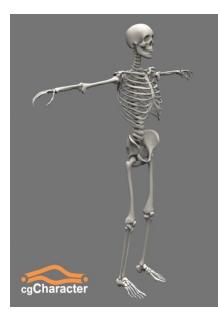
• Realistic model for each layer skeleton, flesh, skin



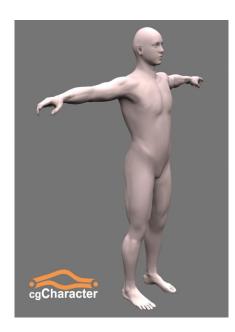


3. Flesh & skin deformation Anatomical simulation

- Advantage : realism, possibility to simulate muscles
- Drawback : computational time!







4. Clothes and hair

Physically-based models

- 1. Difficulties for clothes
 - o Collisions between thin objects
 - Non-extensible: should fold!
 - Numerical integration with stiff springs?
- 2. Difficulties for hair
 - 100 000 strandsExploit spatial coherency!

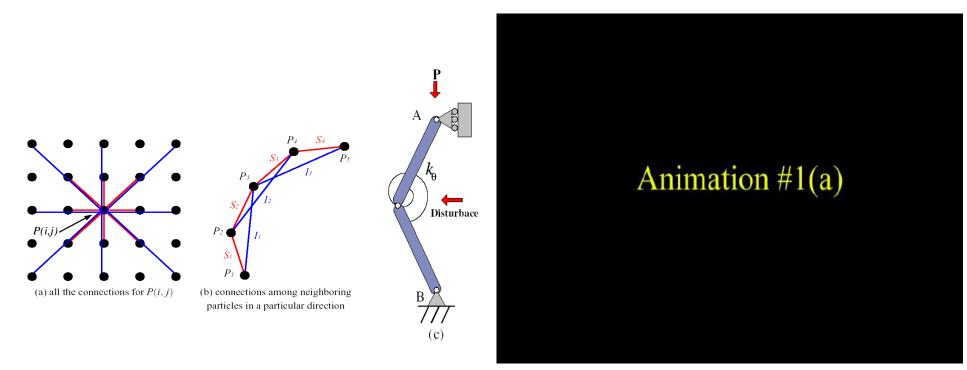




4. Clothes Ease formation of folds

[Choi and Ko 02] Stable but responsive cloth

 \odot Rotation when compression force in the plane of the cloth



Layered model for clothes

[Rohmer, Popa, Cani, Hahmann, Sheffer, SIGGRAPH Asia 2010]



Coarse mesh deformed by convolution skeletons to add folds





Input Simulation

Our results

5. Hair

Hair animation

Physically-based models

- Rigid sticks
- Mass-springs

Geometry

- Hair wisps
- Interpolate between guide hair
- \circ Not realistic without collisions

